



## Quantum control landscapes

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Control of quantum systems, e.g., individual atoms, molecules is an important direction in modern quantum technologies [1–5]. Consider coherent control of an  $N$ -level quantum system which is isolated from the environment. Its dynamics is described by Schrödinger equation:

$$i \frac{dU_t^f}{dt} = (H_0 + f(t)V)U_t^f, \quad U_{t=0}^f = \mathbb{I}.$$

Here  $H_0$  and  $V$  are the free and interaction Hamiltonians (Hermitian  $N \times N$ -matrices such that  $[H_0, V] \neq 0$ ), and  $f \in L_2([0, T], \mathbb{R})$  is a coherent control.

Let  $O$  be a quantum observable (system's Hermitian operator) and  $W \in SU(N)$  be a target unitary operator. Typical quantum control objectives correspond to maximization of average value of  $O$  and generation of target process  $W$  and are characterized by objective functionals

$$\begin{aligned} J_O[f] &= |\text{Tr}(OU_T^f \rho_0 U_T^f)| \rightarrow \max. \\ J_W[f] &= \frac{1}{4} |\text{Tr}(W^\dagger U_T^f)|^2 \rightarrow \max. \end{aligned}$$

Globally optimal controls realize global maximum of the objective. Trap is a control which is optimal only locally but not globally. To establish whether traps exist or not for a given control objective is a highly important practical problem, since they determine the level of difficulty for finding globally optimal controls in numerical and laboratory experiment [5–7].

In [5] it was proposed that quantum control objectives are typically free of traps. However, this property was proved only for  $N = 2$  [8,9] and for control of transmission (that corresponds to  $N = \infty$ ) [10]. Examples of trapping behavior were found for systems with  $N \geq 3$  [6,7].

In [8,9] it was shown that if time  $T$  is large enough then the objective functional  $J_W$  for a qubit has not traps. To explicitly formulate these results, define the special constant control  $f_0$  and the special time  $T_0$ :

$$\begin{aligned} f_0 &:= \frac{-\text{Tr}H_0 \text{Tr}V + 2\text{Tr}(H_0V)}{(\text{Tr}V^2)^2 - 2\text{Tr}(V^2)}, \\ T_0 &:= \frac{\pi}{\|H_0 - \mathbb{I}H_0/2 + f_0(V - \mathbb{I}\text{Tr}V/2)\|}. \end{aligned}$$

*Theorem 1.* For  $N = 2$ , if  $\text{Tr}V = 0$  and  $T \geq T_0$ , then all maxima and minima of the objective functionals  $J_O[f]$  and  $J_W[f]$  are global. Any control  $f \neq f_0$  can not be a trap for any  $T > 0$ .

In [10] it was proved that control of quantum transmission of a particle with energy  $E$  through potential  $V$  is free of traps. For fixed  $E$ , consider  $T_E[V]$  as objective functional of the control potential  $V$ . The control goal is to maximize transmission.

*Theorem 2.* The only extremum of the transmission coefficient  $T_E[V]$  is the value  $T_E = 1$ , i.e.,

$$\frac{\delta T_E}{\delta V} = 0 \Leftrightarrow T_E[V] = 1$$

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In [11,12], small-time control landscapes were studied for the control objective  $J_W$ . The following result was proved [11].

*Theorem 3.* Let  $W \in SU(2)$  be a single qubit quantum gate. If  $[W, H_0 + f_0 V] \neq 0$  then for any  $T > 0$  traps do not exist. If  $[W, H_0 + f_0 V] = 0$  then any control, except possibly  $f \equiv f_0$ , is not trap for any  $T > 0$  and the control  $f_0$  is not trap for  $T > T_0$ .

In [12] it is shown that the control  $f_0$  is not a trap in the case  $T \leq T_0$  and  $[W, H_0 + f_0 V] = 0$ . One can show that it is sufficient to consider  $H_0 = \sigma_z$ ,  $V = v_x \sigma_x + v_y \sigma_y$  and  $W = e^{i\varphi_W \sigma_z}$  without loss of generality. Here  $\sigma_x, \sigma_y, \sigma_z$  are the Pauli matrices,  $v_x, v_y \in \mathbb{R}$  such that  $v = \sqrt{v_x^2 + v_y^2} > 0$ , and  $\varphi_W \in (0, \pi]$ . In this case, the special time is  $T_0 = \frac{\pi}{2}$  and the special control is  $f_0 = 0$ . For fixed  $\varphi_W$  and  $T$  the value of the objective evaluated at  $f_0$  is

$$J_W[f_0] = \cos^2(\varphi_W + T). \quad (1)$$

The control  $f_0 = 0$  is a critical point, i.e., gradient of the objective evaluated at this control is zero. The Taylor expansion of the functional  $J_W$  at  $f_0$  up to the second order has the form:

$$J_W[f_0 + \delta f] = J_W[f_0] + \frac{1}{2} \int_0^T \int_0^T \text{Hess}(t, s) \delta f(t) \delta f(s) dt ds + o(\|\delta f\|_{L_2}^2), \quad \delta f \rightarrow 0,$$

where the integral kernel of Hessian has the form (see [12]):

$$\text{Hess}(s, t) = -2v^2 \cos(\varphi_W + T) \cos(\varphi_W + T - 2|t - s|).$$

We study the spectrum of this integral operator. For this purpose, we consider the following cases:

- $(\varphi_W, T)$  belongs to the triangle domain

$$\mathcal{D}_1 := \left\{ (\varphi_W, T) : 0 < T < \frac{\pi}{2}, \quad \frac{\pi}{2} \leq \varphi_W < \pi - T \right\};$$

- $(\varphi_W, T)$  belongs to the triangle domain

$$\mathcal{D}_2 := \left\{ (\varphi_W, T) : 0 < T \leq \frac{\pi}{2}, \quad \pi - T < \varphi_W \leq \pi, \quad (\varphi_W, T) \neq \left(\frac{\pi}{2}, \pi\right) \right\};$$

- $(\varphi_W, T)$  belongs to the square domain without the diagonal

$$\mathcal{D}_3 := \left\{ (\varphi_W, T) : 0 < T \leq \frac{\pi}{2}, \quad 0 < \varphi_W < \frac{\pi}{2}, \varphi_W + T \neq \frac{\pi}{2} \right\}.$$

*Remark 1.* It is easy to see from (1) that if  $(\varphi_W, T) \in (0, \frac{\pi}{2}] \times (0, \pi] \setminus (\mathcal{D}_1 \cup \mathcal{D}_2 \cup \mathcal{D}_3)$  then  $f_0$  is a point of global extrema of the objective functional  $J_W$ .

*Theorem 4.* If  $(\varphi_W, T) \in \mathcal{D}_1 \cup \mathcal{D}_2 \cup \mathcal{D}_3$  then the Hessian of the objective functional  $J_W$  at  $f_0 = 0$  is an injective compact operator on  $L_2([0, T], \mathbb{R})$ . Moreover,

1. If  $(\varphi_W, T) \in \mathcal{D}_1$ , then Hessian at  $f_0$  is strictly negative.
2. If  $(\varphi_W, T) \in \mathcal{D}_2 \cup \mathcal{D}_3$  then Hessian at  $f_0$  has both negative and positive eigenvalues. In this case, the special control  $f_0 = 0$  is a saddle point for the objective functional.

The second case was previously proved using a different method [11]. The first case is a new result of [12], where it was rigorously proved that in this case  $f_0$  is either a global maximum point or a trap. In [12], also numerical optimization methods were used such as Gradient Ascent Pulse Engineering (GRAPE), differential evolution, and dual annealing to show that the special

control is a point of global maximum if  $(\varphi_W, T) \in \mathcal{D}_1$ . A rigorous proof of this finding remains an open problem. The numerical results also shown that for  $\frac{\pi}{2} \leq \varphi_W \leq \pi$  and  $0 < T \leq \frac{\pi}{2}$  achieving the objective functional value 1, i.e., providing exact generation of phase shift gate, requires a final time  $T$  being not less than the minimal time  $T_{\min} = \pi - \varphi_W$ .

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